

Linear least-squares optimization - Theory

$$y = b_1 x_1 + b_2 x_2 + b_3 x_3 + \dots + b_m x_m$$

y = dependent variable
 x_j = independent variables
 b_j = coefficients to be calculated

Experimental data points: $y_i, x_{i1}, x_{i2}, x_{i3}, \dots, x_{im}$ [$i=1, N$]

Find coefficients b_j by minimizing $S = \sum_{i=1}^N \left(y_i - \sum_{j=1}^m b_j x_{ij} \right)^2$

Example: $y = b_1 + b_2 x + b_3 x^2 + b_4 x^3 + b_5 \ln x$

N experimental points y_i, x_i [$i=1, N$]

Let: $x_{i1} = 1$ $x_{i2} = x_i$ $x_{i3} = x_i^2$ $x_{i4} = x_i^3$ $x_{i5} = \ln x_i$

Example: Gibbs energies: $g^E = \sum \phi_j [X_A X_B^{j+1}]$ N_1 data points

$g_A^E = \sum \phi_j [(X_B - j X_A) X_B^{j+1}]$ N_2 data points

$g_B^E = \sum \phi_j [(j+1) X_A^2 X_B^j]$ N_3 data points

Let: $i=1, N_1$ $y_i = g_i^E$ $x_{ij} = X_{A_i} X_{B_i}^{j+1}$

$i=(N_1+1), (N_1+N_2)$ $y_i = g_{A_i}^E$ $x_{ij} = (X_{B_i} - j X_{A_i}) X_{B_i}^{j+1}$

$i=(N_1+N_2+1), (N_1+N_2+N_3)$: $y_i = g_{B_i}^E$ $x_{ij} = (j+1) X_{A_i}^2 X_{B_i}^j$

SUGGESTIONS FOR OPTIMIZATION

(1) Generally $|G^{E(LIQ)}| < |G^{E(SOL)}|$

(2) Generally $|\Delta h| > |T \Delta s^E|$ $G^E = \Delta H - T \Delta S^E$

(3) $\Delta S_{fusion}^0 \approx 2 \text{ cal/}^\circ\text{K-atom}$ (Richard's Rule)

(4) Solidus data (especially when measured by DTA) are not usually as accurate as liquidus data.

(5) $\Delta S^{ideal} = -R(X_1 \ln X_1 + X_2 \ln X_2) = 1.38 \text{ cal/mol}^\circ\text{K}$ at $X_1 = X_2 = \frac{1}{2}$

Generally $|s^E| < 1.38$
 $k=0.5$